

SKYDIO AUTONOMY ENGINE: ENABLING THE NEXT GENERATION OF AUTONOMOUS FLIGHT

HOT CHIPS, 2021

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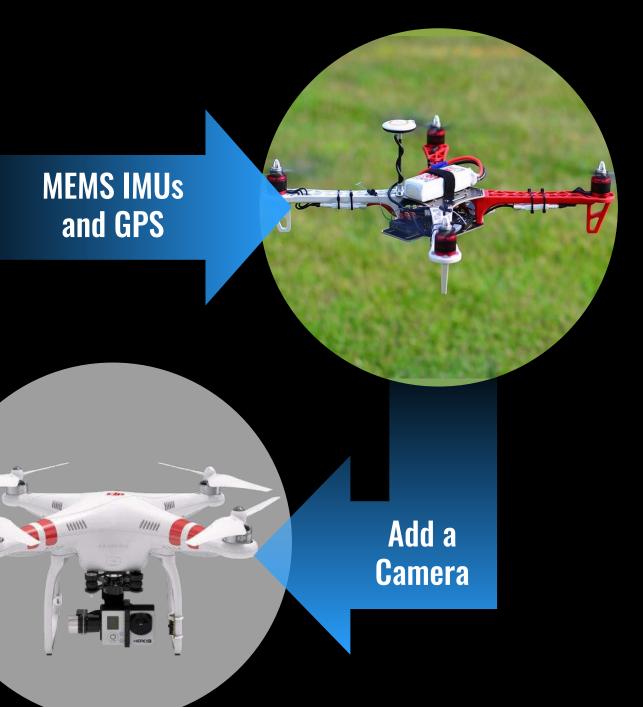
BRIEF HISTORY OF CONVENTIONAL DRONES



Lithium Polymer Batteries

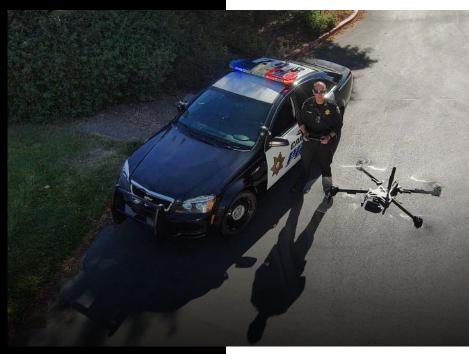




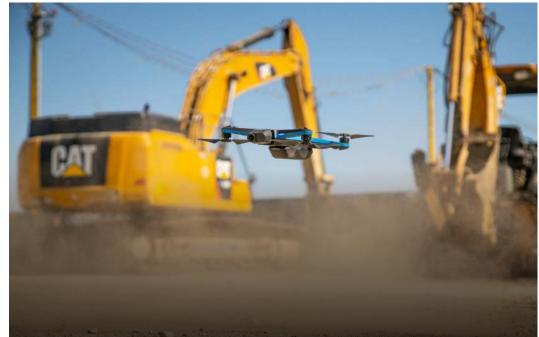


Drones hold the promise of massive positive impact













Drones are 10x More Effective and 100x Cheaper and Safer than Legacy Methods and Heavy Machinery





TOWER INSPECTION



Drones are more versatile and cheaper than camera cranes

Drones are much simpler to deploy and scale than helicopters

safer for inspectors than tower climbs



Drones are much

BRIDGE INSPECTION



Drones are far less disruptive to society than snooper trucks

ECONOMICS OF MANUAL DRONES DON'T SCALE





Up to 80% of an average drone program's budget can be consumed by pilot training and salary



Hard to fly

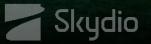


Easy to crash



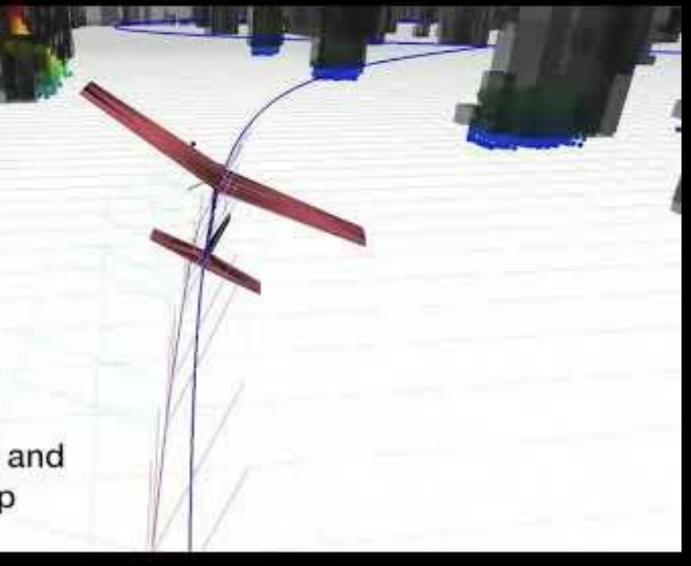
More man hours IN than flight hours OUT

Our roots go back 12+ years with cutting-edge research at MIT's AI lab



MCMXV1

Uses a laser and a known map



OUR MISSION

Make the world more productive, creative, and safe with autonomous flight.









INSPECTION + MAPPING

Digitize the physical world with millimeter precision.

SITUATIONAL AWARENESS

Risk a drone instead of the lives of public safety or service members.

CINEMATOGRAPHY

Capture amazing moments with a Hollywood film crew that fits in your backpack.

The Evolution of Drones

Manual drones have peaked. The future belongs to software-driven aircraft.





- Pilot operated
- RC-based

Skydio



- Pilot operated
- GPS-based
- Sensor payloads

AGE OF AI-DRIVEN AUTONOMY

Software, Al-driven navigation
Native obstacle avoidance
Fully automated workflows
Integrated solutions

Manual Drones

AUTONOMY: BOTTOM LINE

- Existing use cases are easier and more reliable
- New use cases that were previously impossible are enabled



HARDWARE-CENTRIC



Flip phone



Autonomous Drones

SOFTWARE-DRIVEN



Smartphone

CUSTOMER







World-leader in autonomous flight technology

First US drone company unicorn. Over \$340M raised

300+ world class team in Al, robotics, hardware and GTM

Trusted by US DoD, enterprises and everyday consumers







Investors:









Company Heritage:



















WHY CUSTOMERS LOVE SKYDIO A flight experience unlike any other













Automates entire workflows



Skydio is the leading U.S. drone manufacturer and world leader in autonomous flight.

FROST & SULLIVAN

"Skydio is the fastest growing small UAS manufacturer in the world, and is **almost single-handedly re-establishing an industrial base for commercial drones in the United States**...Frost & Sullivan has identified autonomy and AI as the two main technologies that will drive commercial drone adoption in the future and **Skydio is at the forefront** of both."

Michael Blades VP Aerospace, Defense, and Security

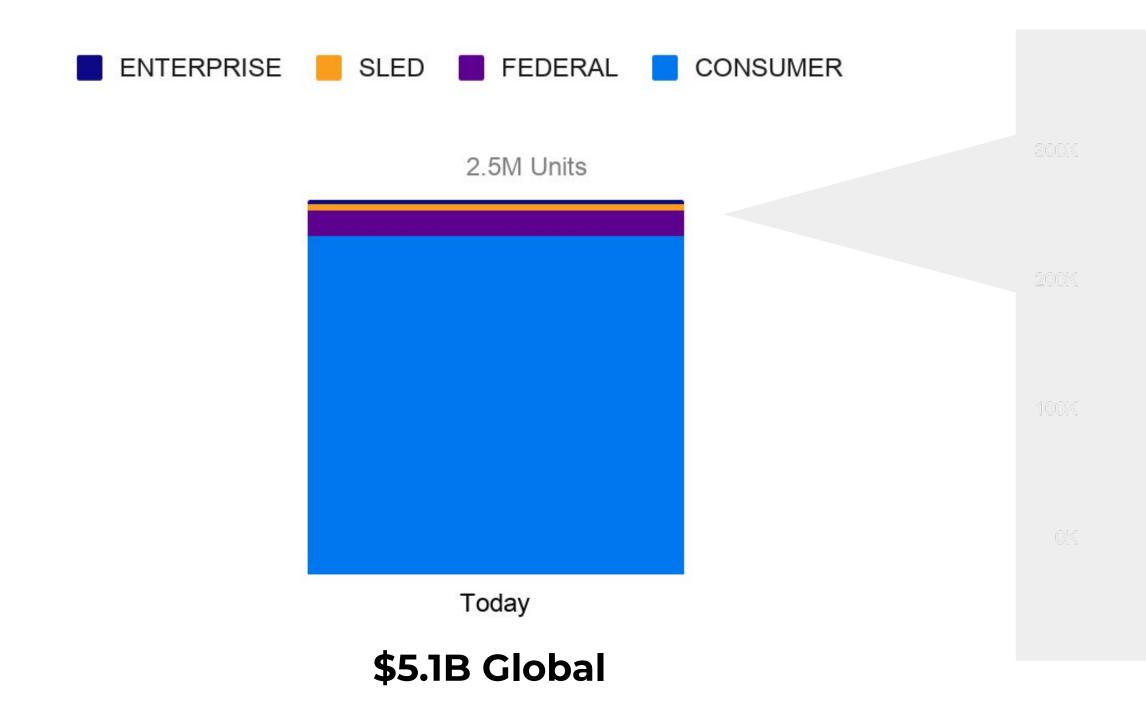


DRONE MARKET INSIGHTS





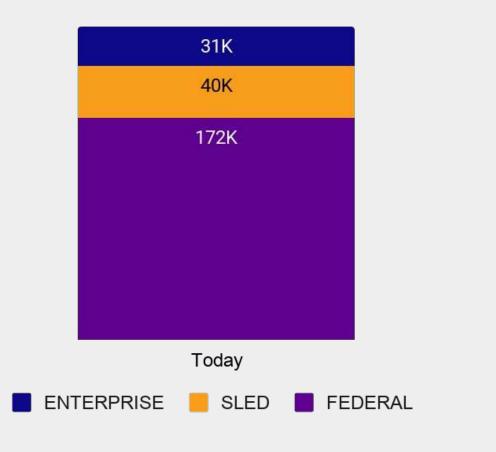
ANNUAL DRONE VOLUMES TODAY





NON-CONSUMER VOLUMES

243K



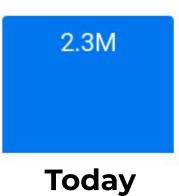
CONSUMER MARKET TODAY VS. POTENTIAL





120M Point and shoot cameras/yr in 2010





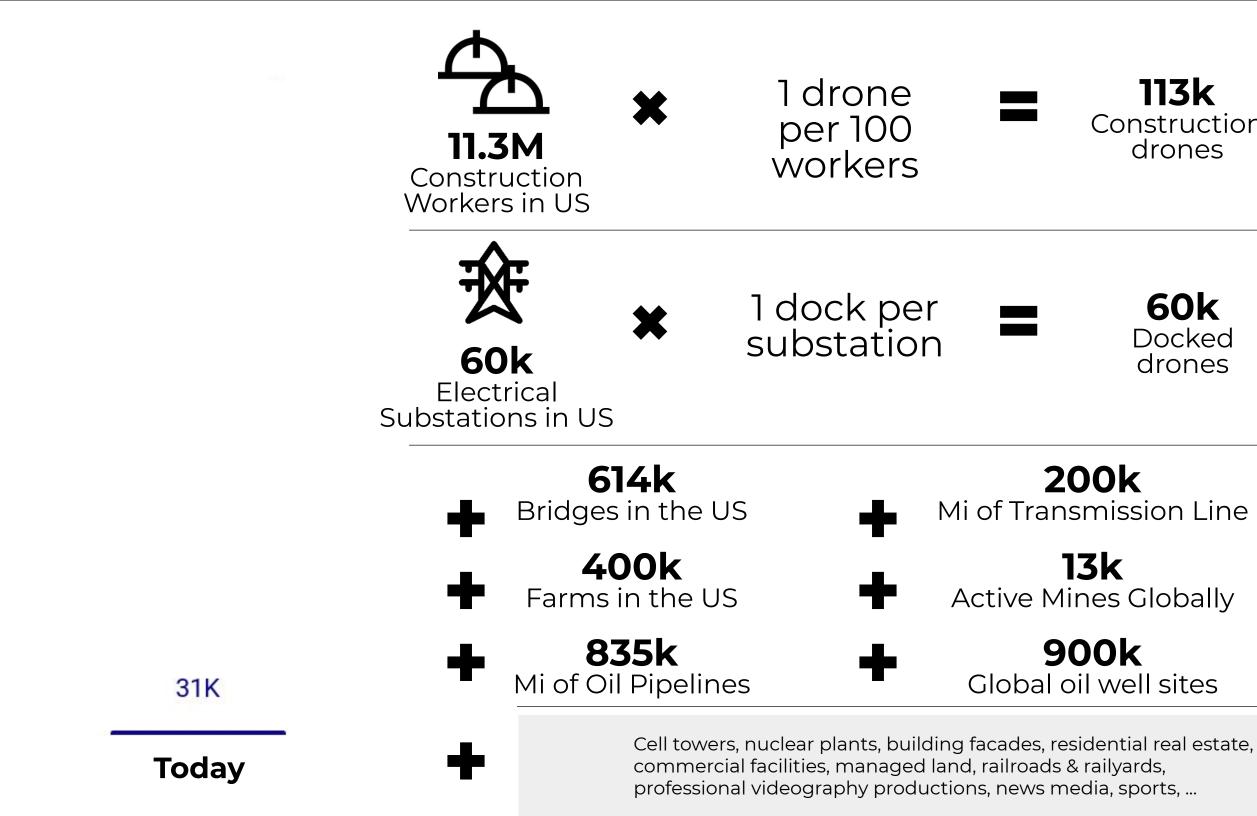






2030+

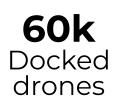
ENTERPRISE MARKET TODAY VS. POTENTIAL

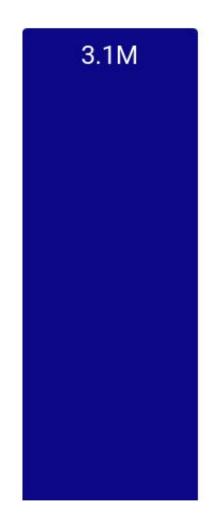






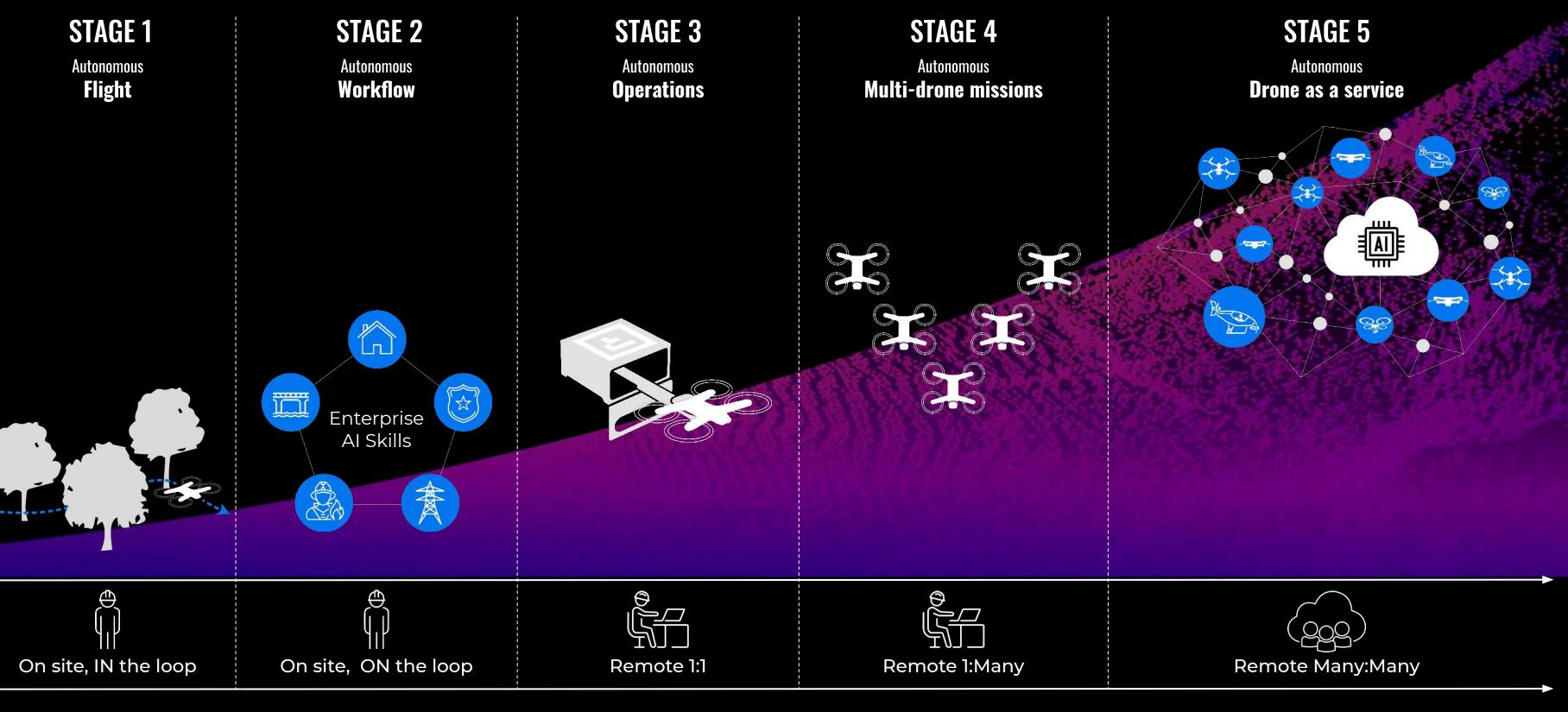
113k Construction drones





2030+

The Arc of Autonomy



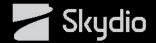
AUTONOMY: FROM TOOLS TO TEAMMATES TO SERVICE

SCALE & VALUE



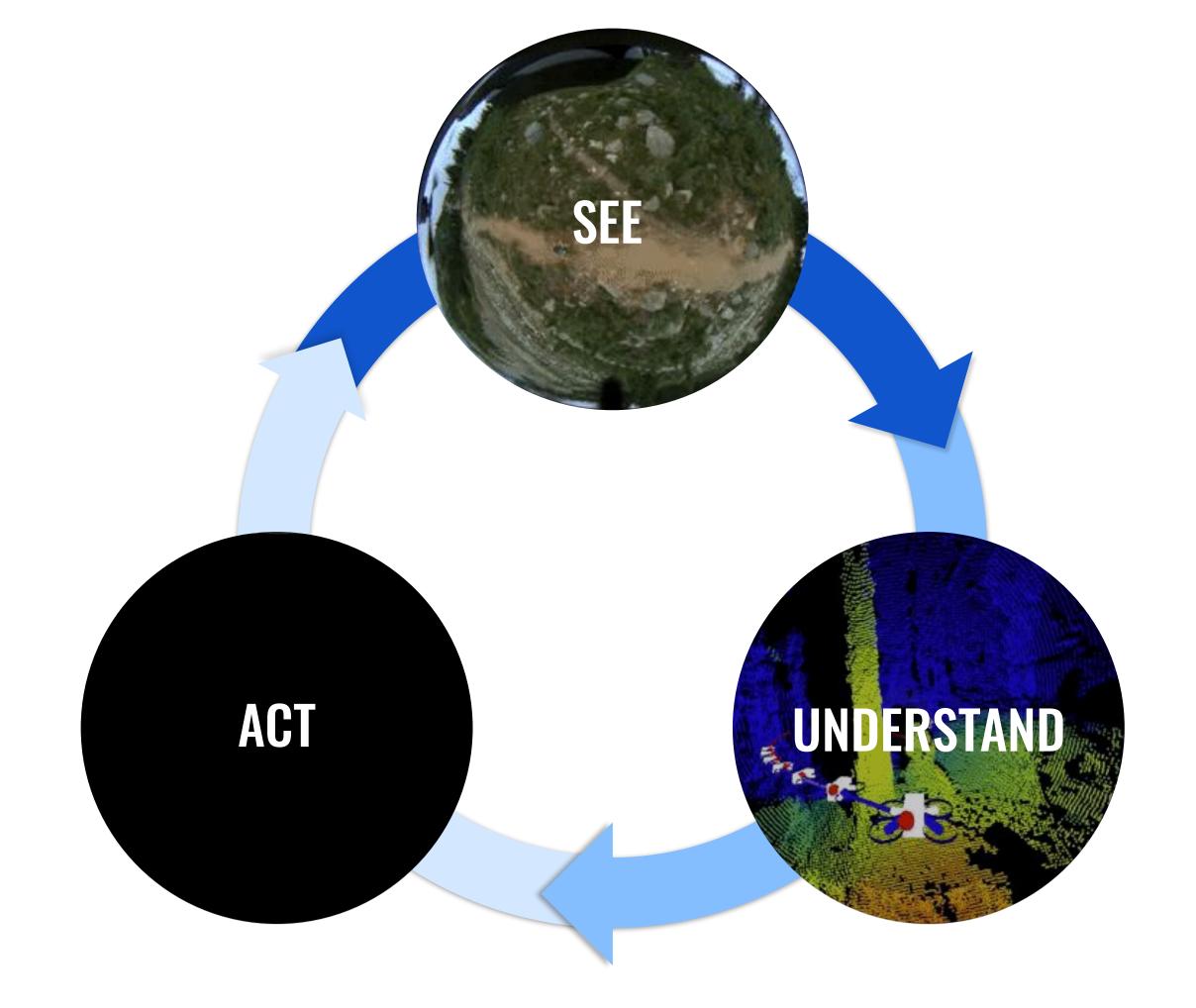


SKYDIO AUTONOMY ENGINE



SKYDIO Autonomytm

A new generation of drone intelligence





SEEING THE WORLD

6x 4K fisheye cameras provide 360 degree coverage





1

K

SKYDIO'S CORE AUTONOMY STACK

Goal: Robust visual navigation in complex, unknown environments across all use cases.

State Estimation - Estimate the robot's motion + sensor calibrations

Obstacle Avoidance - Don't crash into anything

Motion Planning + Control - Dynamic maneuvering with API to support higher level objectives

System Infrastructure - Underlying software platforms to support reliable real-time operation

CHALLENGES

- Computer vision encounters many difficult conditions
- High speed brings complex aerodynamics and little time to respond
- Little room for failure in an autonomous flying system
- Human trust in autonomy is a balance between doing too little and too much
- Constrained compute environment onboard the drone















Vision-based 360 perception at high speed





SKYDIO 3D SCANTM





3D SCANTM

Adaptive scanning solution for autonomous inspection data capture.

- Al-driven workflow
- Adaptive mapping
- Reduced dependence on specialist pilots



Skydio 3D Scan™ Complex structures. Effortless inspections.

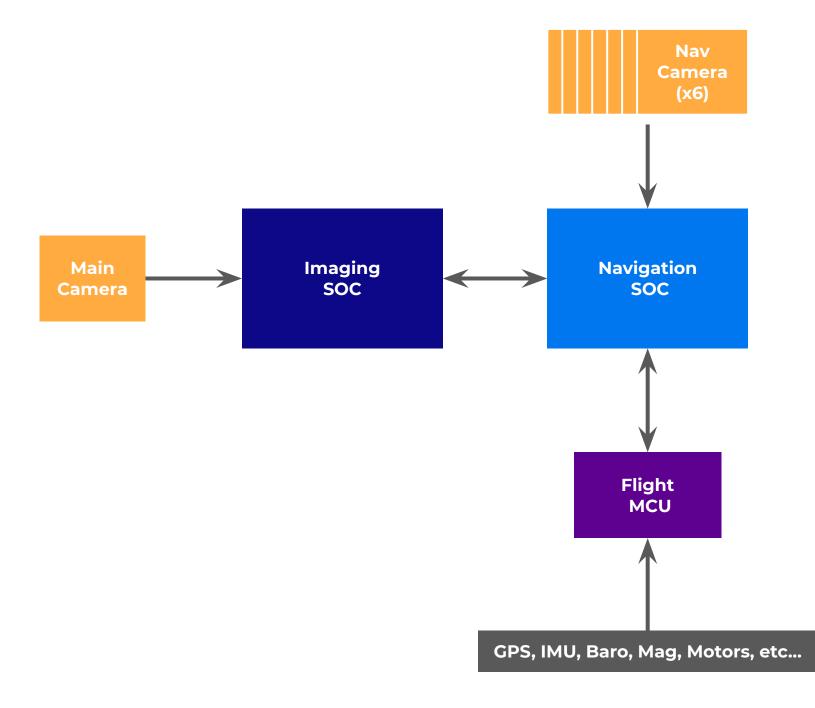


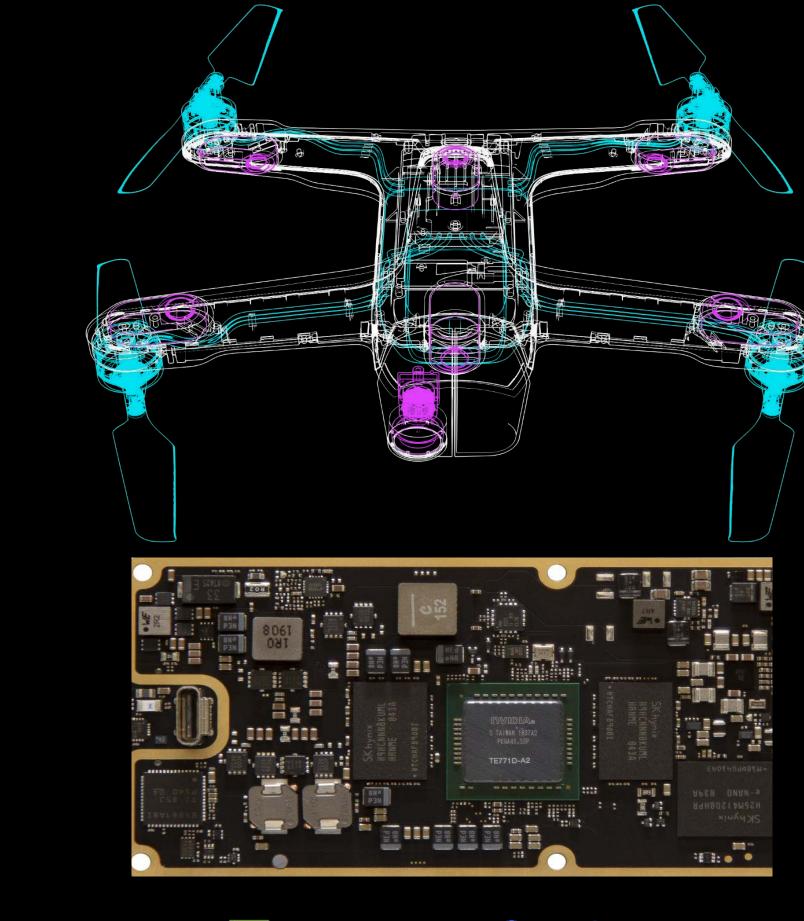


WHAT GOES INTO MAKING AN AUTONOMOUS DRONE?



DRONE HIGH LEVEL Block Diagram









Qualcom

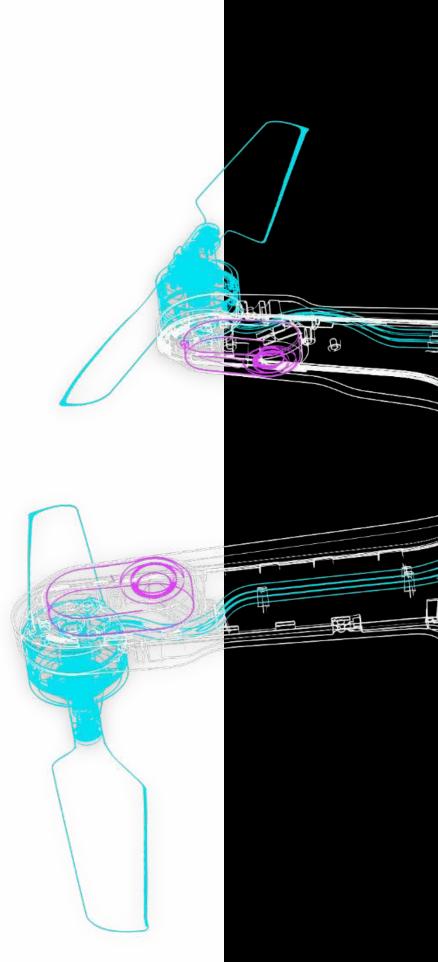
DRONES VS MOBILE Phone electronics

Similarities:

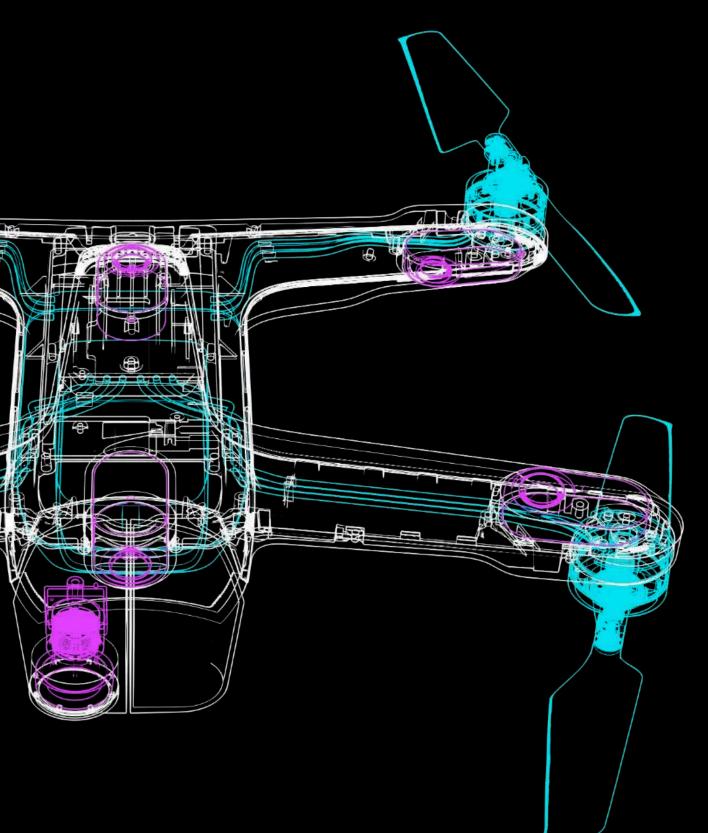
- Size
- Weight
- Cost
- High quality imaging
- Software flexibility is key

Differences:

- More cameras
- Much larger power budget







POWER BUDGET

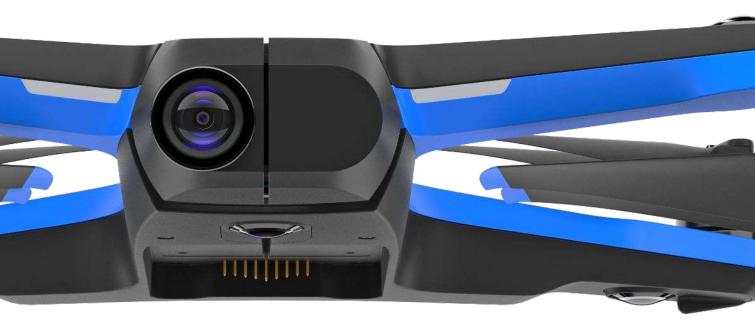
A medium size drone

- Consumes 100-200W
- 20 to 40 minute flight time

1 Watt of compute reduces flight time by ~10s 4g of payload reduces flight time by ~10s

Final compute constraint is mostly driven by size/weight of the board



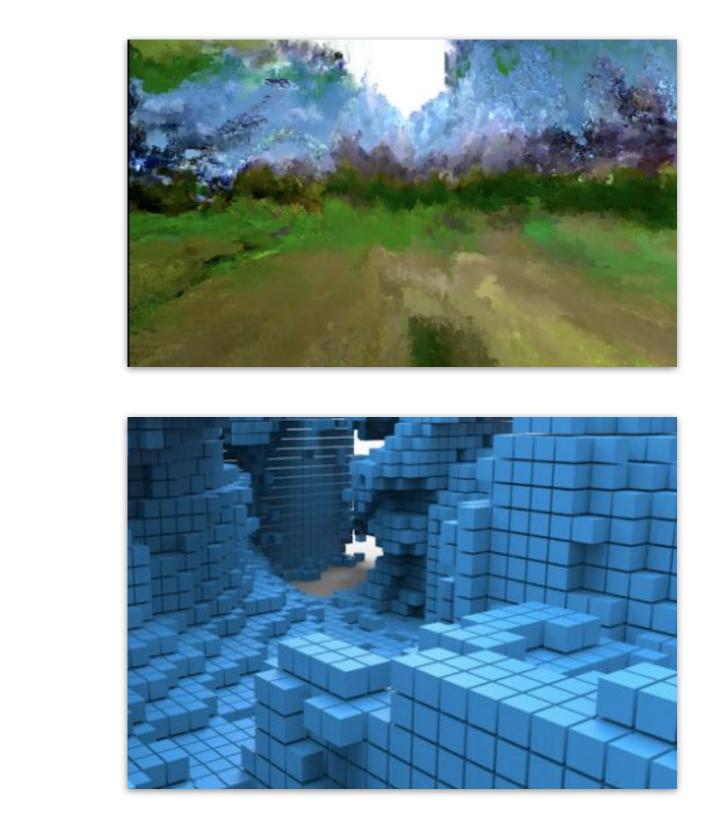


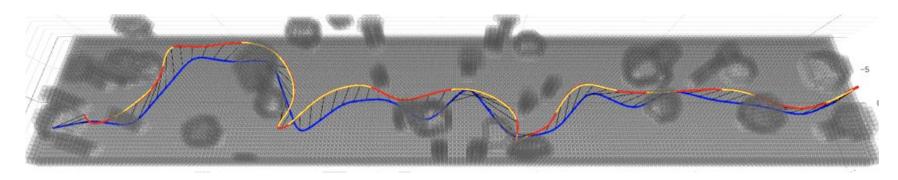




TYPES OF COMPUTE

- High Level Logic/Health Monitoring
- Low-level image processing
- Geometric Computations
- Deep Learning
- Nonlinear Optimization



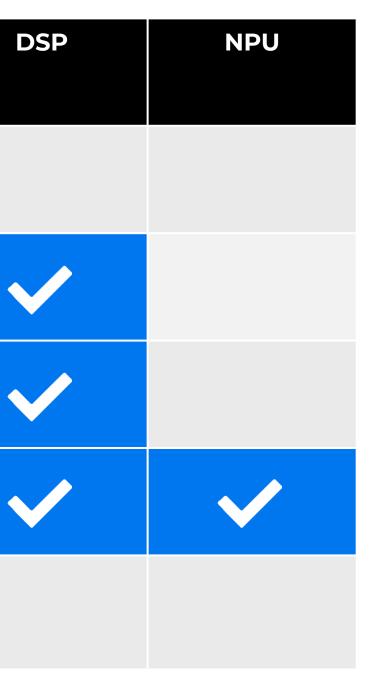




COMPUTE RESOURCE MAPPING

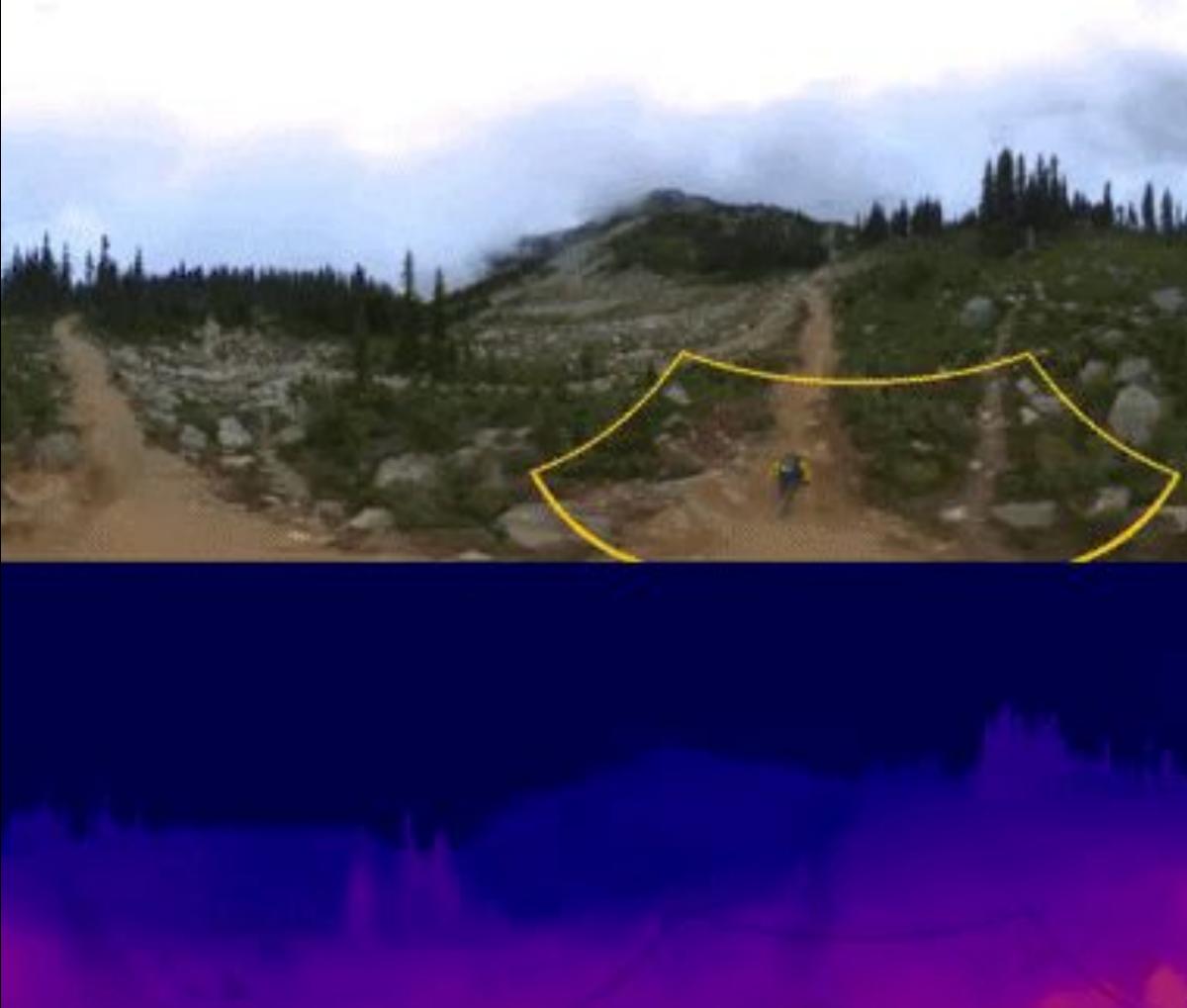
	CPU	ISP	GPU	
HIGH LEVEL LOGIC	\checkmark			
LOW LEVEL IMAGE PROCESSING		\checkmark	\checkmark	
GEOMETRIC COMPUTATIONS				
DEEP LEARNING				
NONLINEAR Optimization	\checkmark			

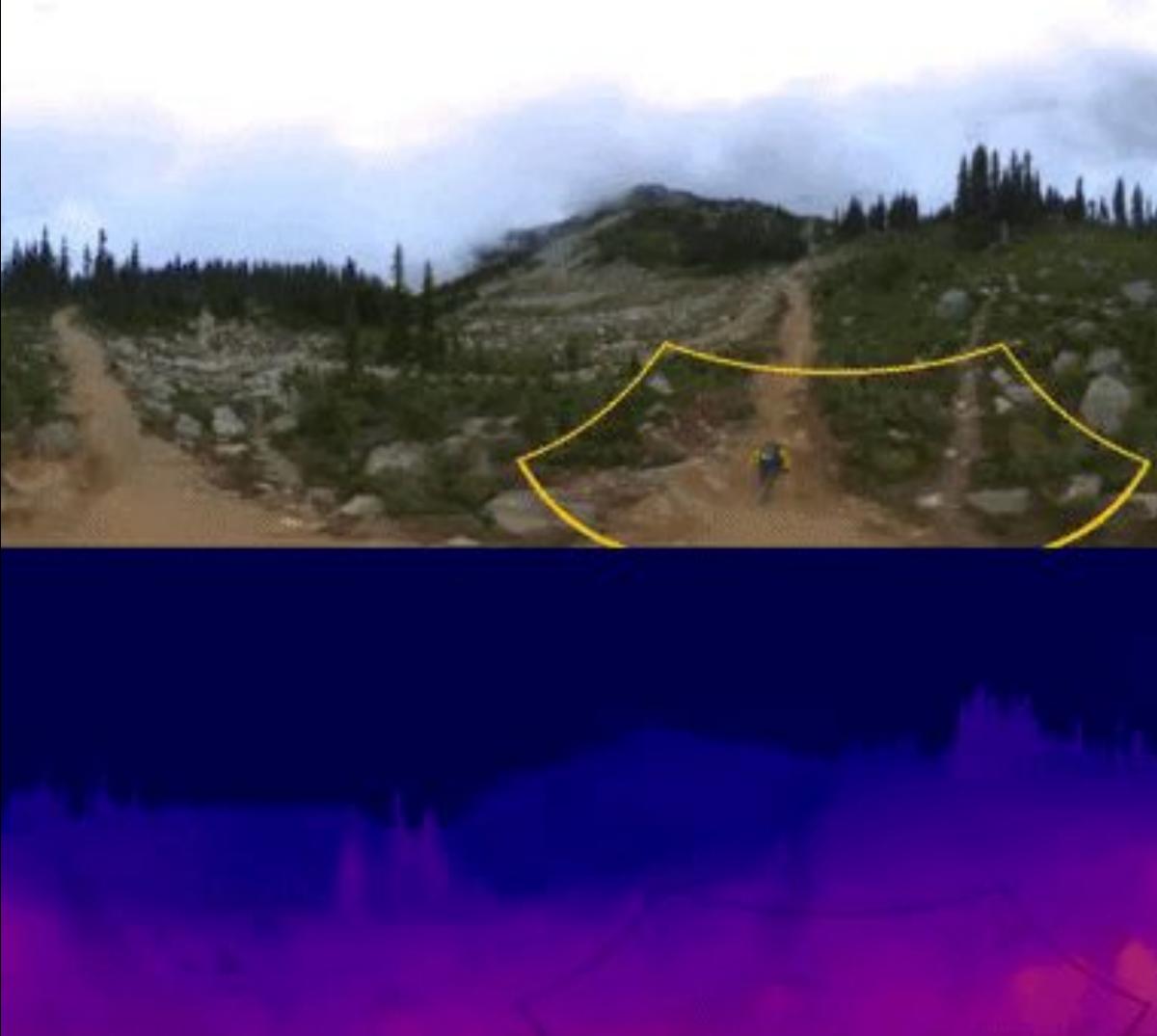




DEEP LEARNING

- 8 models used in flight
- Quantization works great for some
- Need some floating point layers



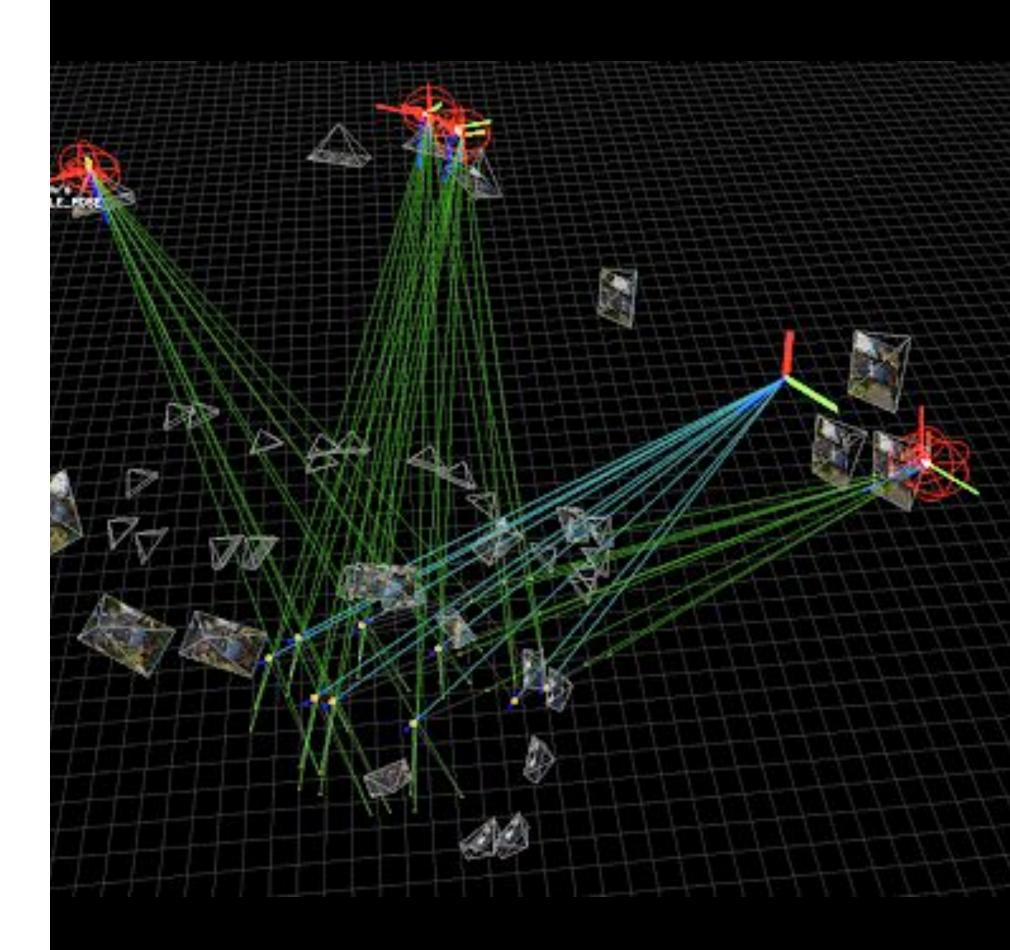




NONLINEAR LEAST-SQUARES OPTIMIZATION

The core of many robotics algorithms

- Visual Odometry
- Simultaneous Localization and Mapping
- System-Identification
- Model Predictive Control



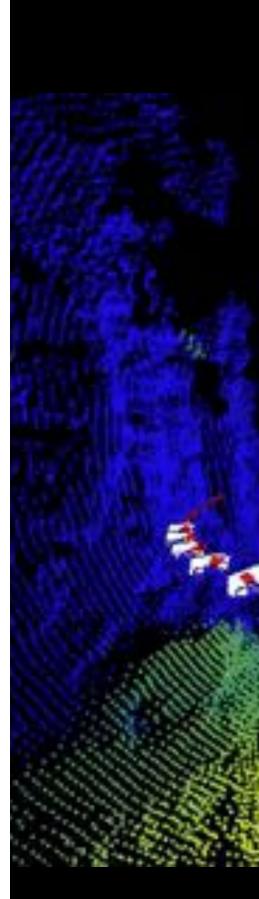


MOTION PLANNING

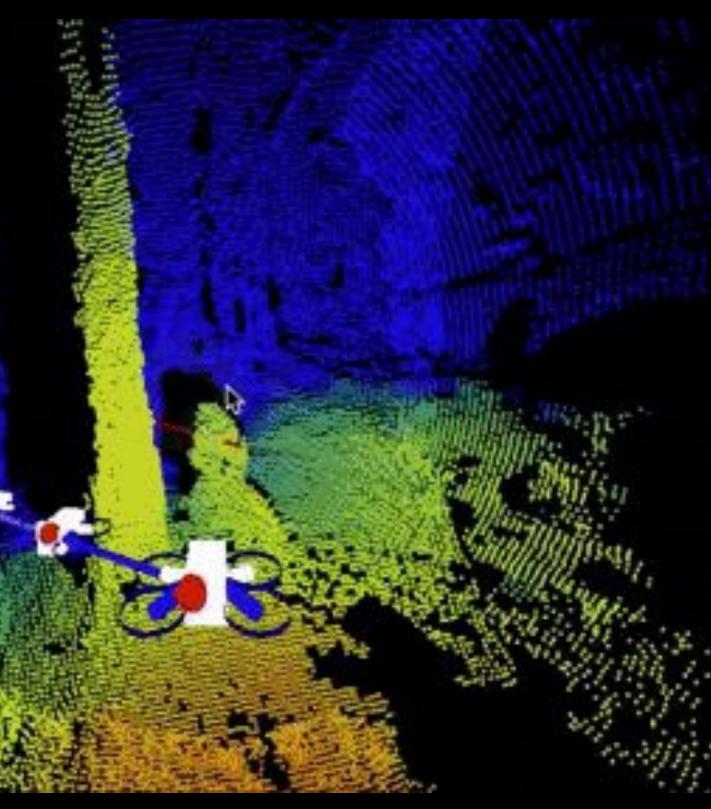
A large optimization problem that jointly solves over 50 objectives including:

- Rotor rates and 6dof vehicle state
- Robot dynamics and aerodynamics
- Obstacles in the world
- Cinematic flight

The optimization is run at 500 iterations a second to ensure fast dynamic response and smooth flight





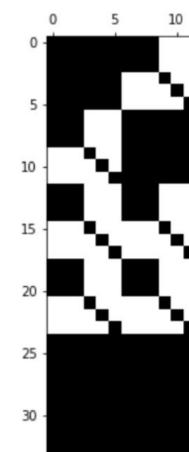


OPTIMIZATION FORMULATION

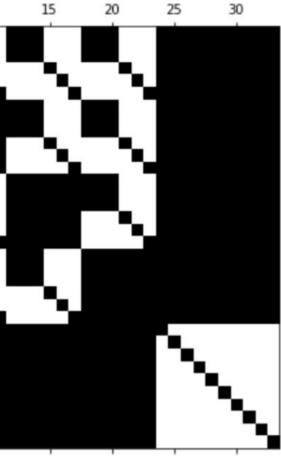
Iterate between:

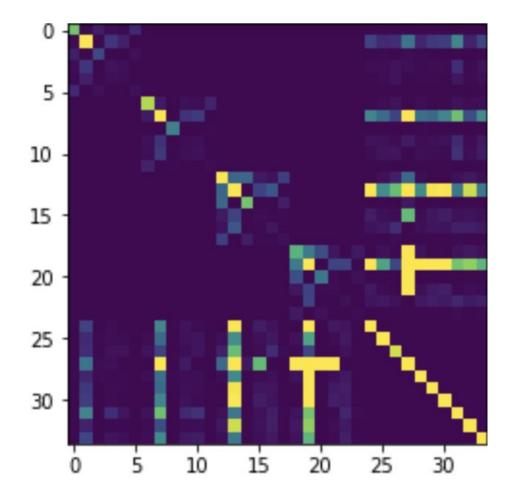
- Linearize the Problem
- Factorize/solve the matrix
 - Medium size and dense
 - Large and sparse

Both steps are compute intensive









SYMBOLIC COMPUTATION

Skydio has developed a custom differential geometry library based on symbolic computation and code generation techniques.

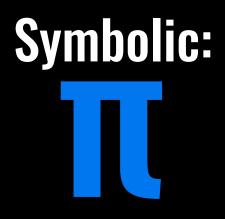
Allows developers to formulate problems with high level symbolic python code

- Avoid handwritten derivatives
- Analytical simplification
- Common subexpression elimination
- Branchless generated code

Yields order of magnitude speed and debuggability gains.







Numeric: 3.14159265359

IMPORTANCE OF Software flexibility

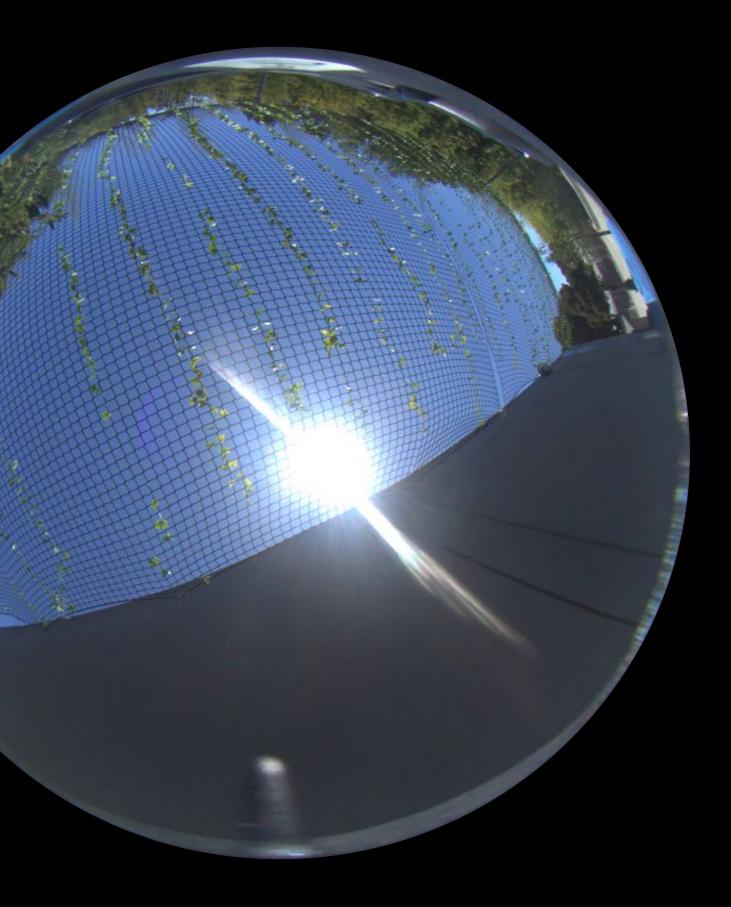
Autonomous systems are VERY early

• Need flexibility to solve the next real world challenges

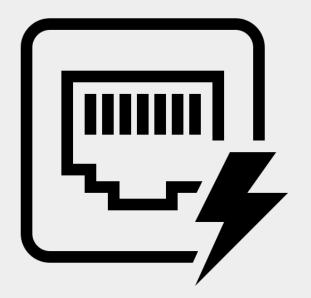
Good software abstractions are key

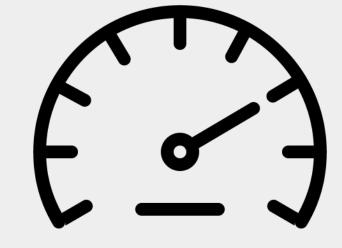
- Close the loop with real world feedback
- Focus on foundational building blocks





WISHLIST FOR FUTURE SOCS





More general compute horsepower

Acceleration of the key workloads





Clean high level abstractions for HW

QUESTIONS?

